Microstrip Line Fed Dielectric Resonator Antenna Optimization using ML Algorithms

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**Abstract: In this communication, a microstrip line fed dielectric resonator antenna is optimized using various Machine learning-based models. Different ML algorithms (such as ANN, KNN, XG Boost, Random Forest, and Decision Tree) are used to optimize the proposed antenna design within the frequency band 3.3-3.65 GHz. |S11| of the proposed antenna is predicted by using various ML algorithms. Dataset for the same is created through HFSS EM simulator by varying the radius, height of DRA as well as the width of microstrip line and conformal strip. Predicted results from all these models are quite close to the actual one except ANN. To overcome the problem of ANN, Knowledge-Based Neural Network techniques (KBNN) are implemented. All these ML algorithms are authenticated by practically constructing and measuring the proposed antenna. Fabricated antenna results have a good agreement with the values predicted by ML algorithms.**

**Keywords- Artificial neural network (ANN), Random Forest, XG boost, K nearest neighbor (KNN), Knowledge-based neural network (KBNN), Dielectric Resonator Antenna, Microstrip Line**

1. **Introduction**

An antenna is the most important component of a wireless communication system. In the modern cellular communication world, an efficient antenna is required which can support high data rate, wider bandwidth, and high-frequency range [1]. For the designing of such an efficient radiator, its different design parameters must be fully optimized. HFSS and CST-MWS are EM simulators, which are widely used for the said purpose. But, the problem with these simulators is the time taken simulation process. This time requirement increases exponentially with advancement in frequency. To overcome this problem, various ML models come into the picture for forecasting the antenna performance at a certain frequency with a very less amount of time [2].

In the open literature, some researchers have focused on this problem and predicted the antenna performance through different ML algorithms. Gao et.al. utilized the Gaussian process, as well as support vector machine for optimization of Yagi Uda, shaped printed antenna and dual-mode printed antenna [3]. Dadashzadeh et.al. obtained the optimum position of shorting pin in a microstrip array through a clustering approach for getting desired polarization characteristics [4]. Lee et.al. proposed the optimization of mutual coupling parameters through ANN in the case of antenna arrays [5]. Sharma et.al. proposed the optimization of T-shaped monopole through LASSO, ANN, and KNN techniques. 450 data set points have been taken to train the model within two different frequency bands i.e. 2.5 GHz and 5.5 GHz [6]. J. P. Jacobs proposed the optimization of a U-shaped slot-loaded microstrip antenna through GPR-based ML algorithms. The aforementioned antenna supports dual frequency bands i.e. 2.75 GHz and 3.75 GHz respectively [7]. Sharma et.al. proposed a compact dual notch loaded patch antenna, which is optimized through Gaussian Process Regression(GPR) based ML model [8].

In this article, the microstrip line fed dielectric resonator antenna is optimized through different ML models such as ANN, KNN, random forest, XG Boost, and decision tree. Two important aspects of the proposed article are: (i) the ML models are applied for the optimization of dielectric resonator antenna, it is the first time; and (ii) the problem associated with ANN is removed by using the KBNN algorithm. The data set is created through the HFSS EM simulator by varying the radius, the height of DRA as well as the width of the microstrip line, and the conformal strip on DRA. Finally, the predicted data is compared with the measured result. The proposed antenna shows a good predicted value within the frequency range of 3.3-3.65 GHz. For better understanding, the proposed article is divided into subsections: Antenna geometrical layout; antenna optimization through ML models; experimental verification, and final conclusion.

1. **Antenna Geometrical Layout**

The proposed antenna structure is shown in Fig.1. Alumina-made cylindrical ceramic is fed through a microstrip line along with a vertical conformal strip. The permittivity of cylindrical ceramic is 9.8. Microstrip line has been printed over FR4 substrate having permittivity 4.4. 3D view and feeding structure of fabricated antenna are shown in Fig. 2. The optimized dimension of the proposed radiator is given in the caption of Fig.1.

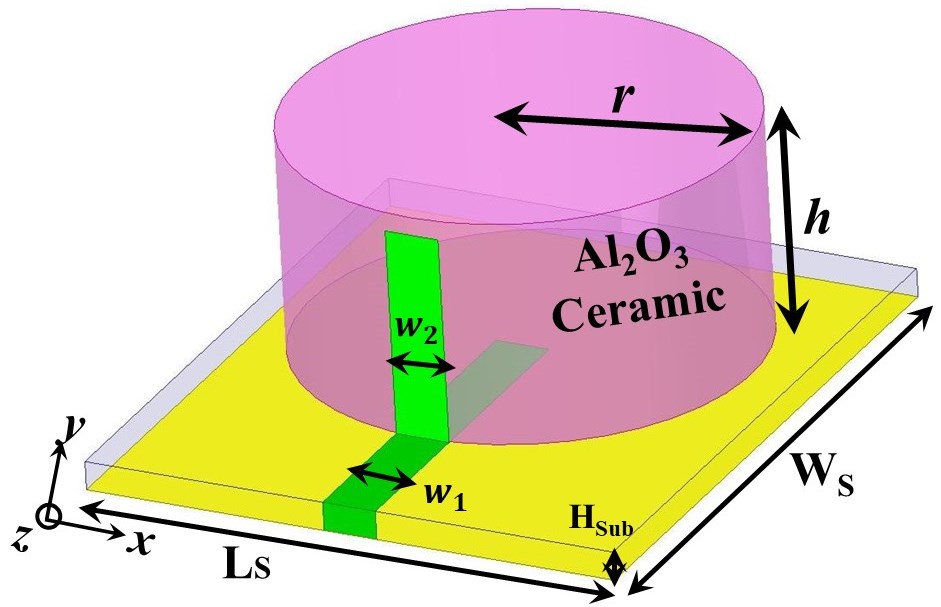


Fig. 1 Microstrip Line fed cylindrical DRA; LS= 30mm; WS= 35mm; w1=3.0 mm; w2=3.0 mm; HSub=1.6 mm; r=12.5 mm; h=12.5 mm

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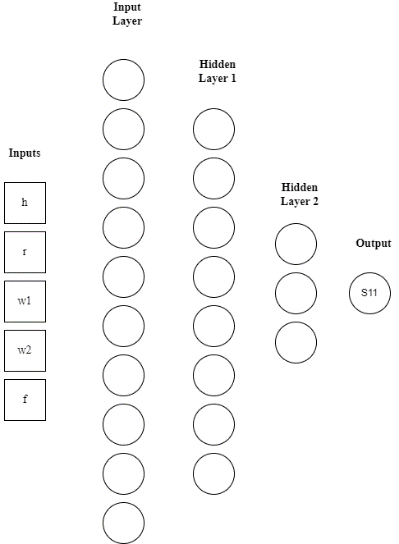
Fig. 2 Pictures of Fabricated Antenna (a) Feeding Structure (b) 3D View

1. **Optimization of Proposed Antenna through ML Models**

For the optimization through ML models, cylindrical DRA has been designed on the Ansys HFSS EM simulator. Few design parameters, which directly affect the reflection coefficient of proposed DRA, are chosen such as height, the radius of DRA, w1 (width of the feed line), and w2 (width of conformal strip). The range and step size selected for *h, r, w1 and w2* are 13mm -14mm: 0.2mm, 13mm-14.2mm: 0.4mm, 2mm-3mm: 0.5mm, 2mm-3mm: 0.5 mm respectively. These ranges are selected by considering the optimized valuse which were obtained from HFSS optimetrics and the proposed dimensions. 216 parameter combinations are generated with these ranges, which mean HFSS will have to perform 216 parameter operations. This process of generating the dataset with such minor iteration count itself shows the inefficiency of using such simulation software for parameter explorations or for complex antenna design optimization. An ML model requires dataset for it’s training, on the basis of whether the dataset is labled or unlabled these models can be categorized into supervised and unsupervised models. The dataset which is generated in our study is labled, so the model undergoes a supervised learning. Learning good values for all the weights and the bias from labelled samples is all that training a model entails. A machine learning algorithm generates a model in supervised learning by studying numerous examples and tries to find a model that minimises loss; this process is known as empirical risk minimization. For Machine Learning models, the generated training dataset has to be separated into training and test sets. This separation is helpful in testing the models for the test data set on which it is never trained on.

It helps in better evaluation of the prediction efficiency of each. For each model, randomly 30% of samples are picked up for test-set. Later, the training data frames are utilized for the training of each model. For implementing KNN, Decision-Tree, and Random-Forest sklearn python library is used, the value of K = 5 was chosen to minimize the cross-validation error. The training process of these models is quick and simple.

Implementation of ANN has been done using *keras* library, which internally uses *tensor-flow* library. There is one input layer with the dimension of 5, as we have five input features for the model with a ‘relu’ activation function. 2 hidden layers are added with the same ‘relu’ activation function. The output layer of unit-1 provides the final result along with the Adam optimizer. Mean squared error (MSE)is used as the loss function for the model.

 Fig: Input, Output and Hidden Layers of ANN

Training of ANN model involves certain hyper-parameters (parameters which controls the learning of a model), two of them are epocs and batch-size. Epocs represent the number of iterations or passes of the model through the entire dataset and batch-size is the size of the training data which have to be worked upon before updating the model’s internal parameters.

Our is carried on for 100 epochs with a batch size of 10. Training of an ANN model is the time-taking process for machines with less compute potential. The training process is also analyzed to have a clear picture of how the model trains itself with the input training data set. Fig. 3 (a) and Fig. 3 (b) display the model loss and model validation loss variation for the ANN model. From Fig. 3 (a) and 3 (b), it can be observed that model loss and model validation loss decrease as the number of epochs increases.

|  |  |
| --- | --- |
| (a) | (b) |

Fig. 3 Loss variation for ANN Model with epoch (a) Model Loss variation (b) Model Validation Loss

After preparing the data set, each ML model can now predict the values of |S11| for a given antenna parameter in a particular frequency band. It’s better to test the model with a data set with which it is not trained. By doing so, we can understand its precision better and analyze the prediction accuracy. If the predictions made are not up to the mark, then any of the following could be the case:

* The training data could be inappropriate or of poor quality.
* A model might require hyper-parameter tuning or some cross-validation.
* The choice of the input features could be wrong.

There might be other reasons even, but for our use case, we tried working on the above-mentioned issues in case of poor model prediction. Prediction metrics provide evaluative and comparative numbers, which helps in opting out the best possible algorithm for a specific use case. The two most relied metrics are the R2-score and MSE (mean absolute error) [9]:

Table-1 contains these accuracy metrics for predictions made by each ML technique. To obtain these values, “*sklearn metrics”* has been used. These metrics provide us a picture of the prediction effectiveness and help in improving the training dataset or tuning the model. From Table-1, it is clearly observed that maximum error is obtained in ANN model, while it is the minimum XG Boost model. Fig. 4 shows the comparison of predicted and the actual result obtained from different ML models i.e. ANN, KNN, XG Boost, Random Forest and Decision Tree. In Fig. 4, the X = Y line represents the ideal case which means the density of points near the line presents a better accuracy result. From Fig. 4, it can be said that there is a close relationship between actual and predicted values for each ML model except ANN. It can also be observed that for smaller values of |S11|, ML models perform well. But, for the values of |S11| near 40-50 dB, there is a minor deviation from the actual values.

Table-1 Prediction Metrics Obtained from different ML Models

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
|  | R2 Score | Mean Absolute Error | Mean Squared Error | Maximum Error |
| ANN | 0.94 | 0.42 | 1.02 | 35.34 |
| KNN | 0.98 | 0.11 | 0.31 | 30.51 |
| Decision Tree | 0.97 | 0.16 | 0.51 | 29.12 |
| Random Forest | 0.99 | 0.13 | 0.32 | 30.03 |
| XG Boost | 0.98 | 0.18 | 0.33 | 13.79 |

|  |  |
| --- | --- |
| (a) | (b) |
| (c) | (d) |
| (e)  Fig. 4 Comparison of Predicted value with actual one (a) ANN (b) Decision Tree (c) KNN (d) Random Forest (e) XG Boost  Table-2 Five Different Random Data Samples for comparison of HFSS results with results predicted from ML models | |

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| Sample | Height (mm) | Radius (mm) | Freq (GHz) | W1 (mm) | W2 (mm) |
| D1 | 14.10 | 14.55 | 2.42 | 2.25 | 2.6 |
| D2 | 13.04 | 13.30 | 1.84 | 2.3 | 2.7 |
| D3 | 13.19 | 13.74 | 1.95 | 2.7 | 2.45 |
| D4 | 14.42 | 13.12 | 2.41 | 2.4 | 2.8 |
| D5 | 13.86 | 14.57 | 2.56 | 2.8 | 2.1 |

Now, to validate the different ML models, randomly take five different datasets and compare the result with HFSS EM simulator. Table-2 lists five different data set for comparing HFSS obtained value with predicted values from different models. Fig. 5 shows the result assessment from HFSS and that from the machine learning models (for all five dataset listed in Table-2). It is clearly observed that the models are found to be acting well. It is perceived from Fig. 5 that the error percentage is in the range 0-7% for all the models.

Fig.5 Graph representing the S11 comparison for each Dataset

The accuracy and prediction capability of ANN should be way more than other implemented ML algorithms, however, in the accuracy analysis, the results are not as expected. Primarily, the low accuracy results of ANN are a reason for less training data-set on which the model was trained. ANN can map complex data relations because of different implied layers. But, the data required for training should have large samples. Generating large training samples through HFSS is not a feasible job. As each iteration requires heavy computation, it makes the process highly inefficient.

However, when the training data is difficult to obtain, the design of experiment (DOE) techniques can also be implied [10], but the data requirement could still be too large. To tackle such issues, some existing models are required. It requires additional prior knowledge and is known as knowledge-based neural network (KBNN). This prior knowledge can be implemented using two different methods: *prior knowledge input* (PKI) and *source difference* [10]*.* In the PKI method, the ANN is trained to map the same input-output relation but along with the training data and other inputs are also added. Additional data is generated using the empirical models, so for PKI the additional training data is generated using *KNN, Decision-Tree, Random-Forest and XGBoost* models. In the source difference method, the ANN is trained on the error (difference) between the HFSS output and the source-model output. The mapping of this error matrix is simpler thus requiring less training. Considering λ as a design parameter vector, for a particular vector the S (λ) is the S11 obtained from HFSS. Similarly, F (λ) obtained from the empirical model. Further, the difference between both results gives the error matrix:

The ANN is now trained on the E (λ), the final required value of S11 can be obtained by summation of the ANN prediction with the empirical model’s output for a parameter vector:

Training efficiency of KBNN supports high dimensional parametric sweeps and design space exploration. Fig 6 (a) and Fig 6 (b) represent the accuracy plot of PKI and Source Difference KBNN models. From Fig. 6, it is clearly observed that there is good relation between predicted and actual value. Table-3 contains the prediction metrics, and provides a comparison of the accuracy performance. Both the KBNN techniques provide better accuracy results as compared to ANN as evident from its MSE and R2 Score. The accuracy results of both the SD and PKI techniques are in close similarity.

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| --- | --- |
| (a) | (b) |

Fig.6 Comparison of Predicted value with actual one (a) KBNN-PKI (b) KBNN-SD

Table-3 MSE and R2 score for ANN, KBNN-PKI and KBNN-SD

|  |  |  |
| --- | --- | --- |
| ML Models | MSE | R2 |
| ANN | 1.02 | 0.94 |
| SD KBNN | 0.51 | 0.97 |
| PKI KBNN | 0.73 | 0.96 |

1. **Experimental Outcomes**

In this section, the predicted outcome is compared with measured results. The reflection coefficient (|S11|) of the proposed antenna is measured through Keysight make VNA E5071C. Fig. 7 shows the measured and simulated |S11| variation with respect to frequency. It is clearly observed from Fig. 7 that there is a good correlation between measured and simulated |S11|. The proposed antenna operates over the frequency range of 3.3-3.65 GHz. In order to find the accountability of resonance at 3.5 GHz, the E-field pattern is displayed in Fig.8. It is perceived from Fig. 8 that HEM11δ mode is generated in cylindrical-shaped ceramic [11]. It is due to the microstrip line feed, which acts as a magnetic dipole [12]. Mathematically, the resonance of the HEM11δ mode can also be verified by using the following empirical formulation [12]:

In eqn. (1), the ‘r’ and ‘h’ is the radius and height of cylindrical ceramic respectively. From eqn. (1), the resonant frequency is found to be 3.35 GHz, which is close to the simulated one.

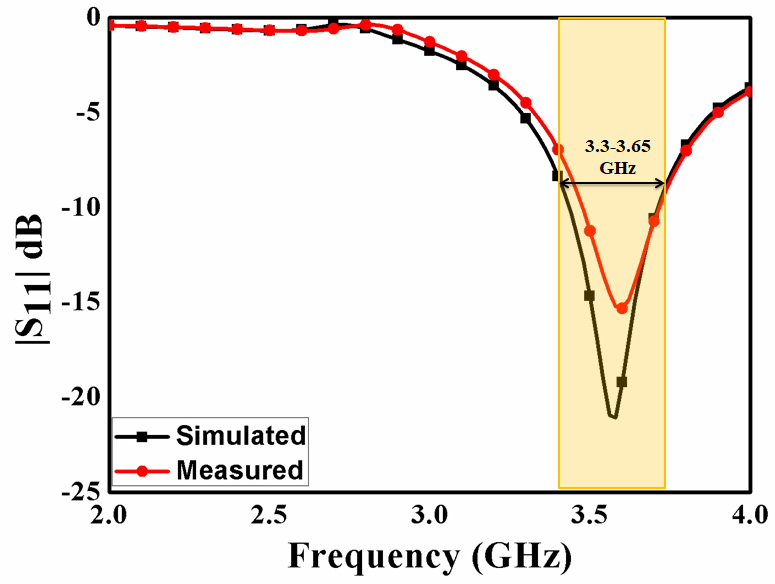


Fig. 7 Measured/Simulated |S11| of the proposed antenna

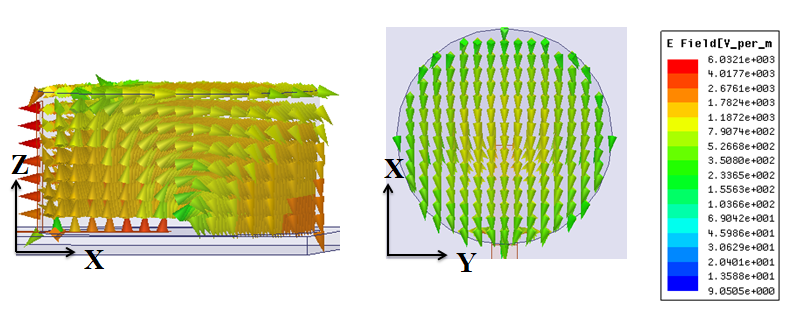


Fig. 8 E-field variation of proposed antenna at 3.5 GHz

Fig. 9 shows the measured/simulated gain variation of the proposed antenna. Gain is measured with the assistance of the two antenna method [13]. From Fig.9, it is observed that the value of gain is about 3.5 dBi within the operating frequency band. Fig. 10 shows the radiation pattern of the proposed antenna in the XZ plane and YZ plane at 3.5 GHz. From Fig. 10, it is clearly observed that broadsided radiation pattern is obtained, which is due to HEM11δ mode in CDRA [11]. There is a good co-pol to cross-pol difference in both the plane.

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Fig.9 Measured/Simulated Gain variation of proposed antenna

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Fig. 10 Far-field pattern of proposed antenna at 3.5 GHz (a) XZ plane (b) YZ plane

1. **Conclusion**

In this article, the microstrip line fed dielectric resonator antenna is optimized through various ML algorithms such as ANN, KNN, random forest, and decision tree. It is the first time when ML models are used to optimize the Dielectric resonator-based radiators. Dataset for the same is created through the HFSS EM simulator. The problem associated with ANN is rectified by using a knowledge-based neural network (KBNN). There is a close prediction obtained with these ML models with actual values (obtained from HFSS). Experimental results further validate the ML models. The proposed antenna works within 3.3-3.65 GHz. The optimized design shows stable radiation characteristics within the operating frequency range and confirms its application for the WiMAX frequency band.

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